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A rigid singularity theorem for spacetimes admitting irrotational reference frames

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Abstract

A rigid singularity theorem for spacetimes admitting irrotational reference frames is proven as an extension of a result (Theorem 3.5) of Petersen and Walschap [Observer fields and the strong energy condition, Class. Quantum Grav. 13 (1996) 1901–1908.]. © 1998 Elsevier Science B.V. All rights reserved.

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Bartnik [1] gave the following splitting conjecture for spatially closed spacetimes:

Conjecture. Let (M, \langle , \rangle) be a globally hyperbolic spacetime which contains a compact spacelike hypersurface S and obeys the strong energy condition, $\operatorname{Ric}(z, z) \geq 0$ for all timelike vectors z. If (M, \langle , \rangle) is timelike geodesically complete, then (M, \langle , \rangle) splits isometrically into the product $(\mathbb{R} \times N, -dt^2 \oplus h)$, where (N, h) is a compact Riemannian manifold.

The conjecture may also be interpreted as a rigid singularity theorem: unless spacetime splits, spacetime must be singular, that is, timelike geodesically incomplete. (See [4] for the progress shown in proving this conjecture.)

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In this short communication, we give an extension of a result of Petersen and Walschap [5, Theorem 3.5] to a rigid singularity theorem similar to the above conjecture for spacetimes admitting a certain type of irrotational reference frame. We prove the following theorem:

Theorem 1. Let Z be an irrotational reference frame on a spacetime (M, \langle , \rangle) with achronal, compact, simply connected restspaces. If Z div $Z \ge 0$ and $\operatorname{Ric}(Z, Z) \ge 0$ on M then either (M, \langle , \rangle) is timelike geodesically incomplete, or else (M, \langle , \rangle) splits isometrically as a product $(\mathbb{R} \times N, -dt^2 \oplus h)$, where (N, h) is a compact simply connected Riemannian manifold.

We essentially repeat the proof of Petersen and Walschap [5, Theorem 3.5] in the first half of the proof of the above theorem. The second half of its proof is inspired from Fischer [3].

Recall that a future-directed unit timelike vector field Z on a spacetime (M, \langle , \rangle) is called a *reference frame*. The orthogonal bundle Z^{\perp} to Z is called the *restbundle* of Z. For a reference frame Z, the bundle homomorphism $A_Z : Z^{\perp} \rightarrow Z^{\perp}$ is defined by $A_Z X = -\nabla_X Z$ for every $X \in \Gamma Z^{\perp}$ (cf. [8, p. 55]). A reference frame Z is called *irrotational* if A_Z is self-adjoint. This is equivalent to that Z^{\perp} is integrable (cf. [5, Proposition 2.1]). In this case, inextendable integral manifolds of Z^{\perp} are called the *restspaces* of Z. Note that, if Z is an irrotational reference frame then A_Z is the shape operator of the restspaces of Z. Moreover, note also that the *acceleration* $\nabla_Z Z$ of Z is a vector field tangent to the restspaces of Z. In [5], the following interesting observation is made:

Lemma 1 [5, Lemma 3.4]. Let Z be an irrotational reference frame and let $\omega(\cdot) = \langle \cdot, \nabla_Z Z \rangle$. Then the restriction of ω to any restspace of Z is closed.

To prove Theorem 1, we also need a lemma concerning the flows of complete vector fields. Let Z be a complete vector field on a manifold M and $\Phi : \mathbb{R} \times M \to M$ be its flow. Hence if we define $\Phi_t(p) = \Phi(t, p)$ then $\Phi_t(p) = c_p(t)$, where $c_p(t)$ is the integral curve of Z with $c_p(0) = p$. Also note that $\Phi_t : M \to M$ is a 1-parameter group of diffeomorphisms of M parametrized over \mathbb{R} .

Lemma 2 [3, Proposition 6.1]. Let Z be a complete vector field on a manifold M and let $\Phi : \mathbb{R} \times M \to M$ be its flow. If $(a, v) \in T_{(t,p)}(\mathbb{R} \times M)$ then

$$\Phi_{*(t,p)}(a,v) = a(Z \circ \Phi_t)(p) + (\Phi_t)_{*p}v,$$

where $(Z \circ \Phi_t)(p) = Z_{\Phi_t(p)} = Z_{c_p(t)}$.

Proof of Theorem 1. Let $\{X_1, \ldots, X_n\}$ be an adapted moving frame near $p \in M$, that is, $\{X_1, \ldots, X_n\}$ is a Lorentzian basis frame near p with $(\nabla X_i)_p = 0$ for $i = 1, \ldots, n$ (cf. [7, p. 152]). Then at $p \in M$,

E. García-Río, D.N. Kupeli/Journal of Geometry and Physics 28 (1998) 158–162

$$Z \operatorname{div} Z = \sum_{i=1}^{n} \langle X_i, X_i \rangle Z \langle \nabla_{X_i} Z, X_i \rangle = \sum_{i=1}^{n} \langle X_i, X_i \rangle \langle \nabla_Z \nabla_{X_i} Z, X_i \rangle$$
$$= \sum_{i=1}^{n} \langle X_i, X_i \rangle \langle R(Z, X_i) Z, X_i \rangle + \sum_{i=1}^{n} \langle X_i, X_i \rangle \langle \nabla_{X_i} \nabla_Z Z, X_i \rangle$$
$$- \sum_{i=1}^{n} \langle X_i, X_i \rangle \langle \nabla_{\nabla_{X_i} Z} Z, X_i \rangle$$
$$= -\operatorname{Ric}(Z, Z) + \operatorname{div} \nabla_Z Z - \operatorname{tr}(\nabla Z)^2.$$

Also, since $\langle (\nabla Z)^2 Z, Z \rangle = 0$, tr $(\nabla Z)^2 =$ tr A_Z^2 , and we have

$$Z \operatorname{div} Z = -\operatorname{Ric}(Z, Z) + \operatorname{div} \nabla_Z Z - \operatorname{tr} A_Z^2$$

Now let N be a restspace of Z. Then along N, we have

$$\operatorname{div} \nabla_Z Z = \| \nabla_Z Z \|^2 + \operatorname{div}_N \nabla_Z Z,$$

where div_N is the divergence in the induced Riemannian structure of (N, \langle , \rangle) . Thus along a restspace N of Z, we have

$$Z \operatorname{div} Z = -\operatorname{Ric}(Z, Z) + \| \nabla_Z Z \|^2 + \operatorname{div}_N \nabla_Z Z - \operatorname{tr} A_Z^2.$$
(1)

Hence by the assumptions $Z \operatorname{div} Z \ge 0$, $\operatorname{Ric}(Z, Z) \ge 0$ and the fact that tr $A_Z^2 \ge 0$ (since A_Z is self-adjoint), it follows that

$$\|\nabla_Z Z\|^2 + \operatorname{div}_N \nabla_Z Z \ge 0$$

on every restspace N of Z.

Now let $\omega(\cdot) = \langle \cdot, \nabla_Z Z \rangle$ be the metrically equivalent 1-form to $\nabla_Z Z$ on (M, \langle , \rangle) . Then by Lemma 1, the restriction of ω to a restspace N is closed and then it follows from the simple connectivity of N that there exists a function f on N such that $\nabla_Z Z = \operatorname{grad}_N f$ on N, where grad_N is the gradient in the induced Riemannian structure of (N, \langle , \rangle) . Hence, if we denote the Laplacian in (N, \langle , \rangle) by Δ_N , we have

$$\Delta_N e^f = -(\|\nabla_Z Z\|^2 + \operatorname{div}_N \nabla_Z Z) e^f \leq 0.$$

Thus e^f is a subharmonic function on (N, \langle , \rangle) and since N is compact, it follows that e^f is constant on N, that is, f is constant on N. But then it follows that $\nabla_Z Z = 0$ along N, that is, Z is geodesic reference frame along N and consequently, it follows from (1) that tr $A_Z^2 = 0$ along N, that is, $A_Z = 0$ along N and hence N is totally geodesic. Consequently, we have two totally geodesic foliations on (M, \langle , \rangle) , one by the integral curves of Z and the other by the restspaces of Z. Now suppose (M, \langle , \rangle) is timelike geodesically complete. Then since Z is a geodesic reference frame, Z is complete on M, and let $\Phi : \mathbb{R} \times M \to M$ be its flow. Now let N be a restspace of Z and define

$$\boldsymbol{\Phi}^0 = \boldsymbol{\Phi}|_{\mathbb{R}\times N} : \mathbb{R}\times N \to U \subseteq M,$$

160

where U is the image of Φ^0 . First we observe that $\Phi^0(\{t\} \times N) = \Phi_t(N)$ is also a restspace of Z for all t. For, let X_0 be a vector field on N and let X be a vector field on U defined by $X_{\Phi_t(p)} = (\Phi_t)_* X_0$. (Note that, since the achronality of the restspaces of Z implies that (M, \langle , \rangle) is chronological, integral curves of Z are injective and hence the vector field X is well-defined). Then since [Z, X] = 0,

$$Z\langle Z, X\rangle = \langle Z, \nabla_Z X\rangle = \langle Z, \nabla_X Z\rangle = 0.$$

That is, X is orthogonal to Z. Hence since Φ_t is nonsingular for each t, $(\Phi_t)_*$ isomorphically maps the tangent space of N at p to $Z_{\Phi_t(p)}^{\perp}$. Thus by the uniqueness of the restspace passing from $\Phi_t(p)$, it follows that $\Phi_t(N)$ is also a restspace of Z (since N is compact). Next we will show that Φ^0 is a local diffeomorphism onto its image. Now let $(a, v) \in T_{(t,p)}(\mathbb{R} \times N)$. Then by Lemma 2,

$$\Phi^{0}_{*(t,p)}(a,v) = \Phi_{*(t,p)}(a,v) = a(Z \circ \Phi_{t})(p) + (\Phi_{t})_{*p}v.$$

Hence since $0 \neq Z_{\Phi_t(p)}$ and $(\Phi_t)_* v \in T_{\Phi_t(p)} \Phi_t(N)$ are orthogonal, if $\Phi_{*(t,p)}^0(a, v) = 0$ then it follows that (a, v) = 0, that is, Φ^0 is a local diffeomorphism. Finally we show that Φ^0 is injective. Let $(t_1, p_1), (t_2, p_2) \in \mathbb{R} \times N$ such that $\Phi^0(t_1, p_1) = \Phi^0(t_2, p_2)$. Then since $\Phi_{t_1-t_2}(p_1) = p_2$, we have two possibilities. The first one is $t_1 = t_2$. In this case, since $\Phi_0 = id$, it follows that $p_1 = p_2$. The second one is $t_1 \neq t_2$. But this case is not possible since then there exists an integral curve of Z from p_1 to p_2 in contradiction to the achronality of N. Thus Φ^0 is a diffeomorphism of $\mathbb{R} \times N$ onto U. Hence since the foliations determined by the integral curves of Z and the restspaces of Z in U are totally geodesic, it follows from [6, Proposition 3-d] that (U, \langle , \rangle) splits isometrically to a product $(\mathbb{R} \times N, -dt^2 \oplus h)$, where h is the induced Riemannian matric on the restspace N of Z. But note that since (N, h) is a complete Riemannian manifold, (U, \langle , \rangle) is geodesically complete and hence is an inextendable spacetime (see [2, p. 220]). Thus $(U, \langle , \rangle) = (M, \langle , \rangle)$.

Remark 1. Note that a reference frame Z is called *rigid* if A_Z is skew adjoint. Hence for a rigid reference frame Z, div $Z = -\text{tr } A_Z = 0$. Thus we also have the following special case of Theorem 1. (Also compare with [5, Proposition 4.3].)

Theorem 2. Let Z be an irrotational, rigid reference frame on a spacetime (M, \langle , \rangle) with achronal, compact, simply connected restspaces. If $\text{Ric}(Z, Z) \ge 0$ on M then either (M, \langle , \rangle) is timelike geodesically incomplete, or else (M, \langle , \rangle) splits isometrically as a product $(\mathbb{R} \times N, -dt^2 \oplus h)$, where (N, h) is a compact simply connected Riemannian manifold.

Acknowledgements

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